

**TECHNICAL APPENDIX**

**Solving the Stochastic Growth Model with a Finite Element Method**

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Details of the calculation of approximate consumption functions for the stochastic growth model are provided below.

1. *Initialization.*

- i.* specify parameters of utility and production:  $\beta, \delta, \tau, \rho, \alpha,$  and  $\sigma_\epsilon$ ;
- ii.* specify the grid on capital:  $\vec{k} = [k_1, k_2, k_3, \dots, k_{n_k}]$ ;
- iii.* specify the grid on technology:  $\vec{\theta} = [\theta_1, \theta_2, \dots, \theta_{n_\theta}]$ ;
- iv.* specify an initial guess for consumption:  $c(k_i, \theta_j)$  for each  $k_i, \theta_j$  pair where  $k_i, i = 1, \dots, n_k,$  is an element of  $\vec{k}$  and  $\theta_j, j = 1, \dots, n_\theta,$  is an element of  $\theta_j$ ; let  $c_a$  denote consumption at grid point (or *node*)  $a$  and  $\vec{c}$  is the vector with elements  $c_a, a = 1, \dots, nnodes, nnodes = n_k n_\theta$ ;
- v.* specify parameters for quadrature:
  - a. for integration with respect to  $\epsilon,$  specify  $[\underline{\epsilon}, \bar{\epsilon}]$  and  $m_\epsilon$ ;
  - b. for integration with respect to  $k$  on interval  $[k_i, k_{i+1}],$  specify  $m_{k,i}$ ;
  - c. for integration with respect to  $\theta$  on interval  $[\theta_i, \theta_{i+1}],$  specify  $m_{\theta,i}$ ;
- vi.* specify the maximum number of iterations of the Newton-Raphson algorithm and a criterion for stopping iterations (i.e., a norm  $\|\cdot\|$  and a tolerance parameter).

2. *Calculation of abscissas and weights for quadrature.*

- i.* given parameters of step 1(*v*), calculate abscissas and weights for integration done in step 3. (See Press, et.al. (1986) for details.)

3. *Main loop.*

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do  $t = 1$  to maximum number of iterations
  set  $H = 0, J = 0$  where  $H$  is  $nnodes \times 1$  and  $J$  is  $nnodes \times nnodes$ 
  do  $e = 1$  to number of elements ( $=(n_k - 1)(n_\theta - 1)$ )
    determine current intervals for  $k, \theta$  in element  $e$ 
    determine the 4 global nodes for element  $e$  (call them nodes 1-4)
    do  $j = 1$  to number of quadrature points for  $\theta$  on element  $e$ 
      do  $i = 1$  to number of quadrature points for  $k$  on element  $e$ 
        calculate consumption  $c$  (for  $(i, j)$ th quadrature point in element  $e$ )

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e.g., if  $(k, \theta)$  are the current coordinates and element  $e$  is given by  $[\underline{k}_e, \bar{k}_e] \times [\underline{\theta}_e, \bar{\theta}_e]$ , then

$$c = c_{\text{node1}} \frac{\bar{k}_e - k}{\bar{k}_e - \underline{k}_e} \cdot \frac{\bar{\theta}_e - \theta}{\bar{\theta}_e - \underline{\theta}_e} + c_{\text{node2}} \frac{k - \underline{k}_e}{\bar{k}_e - \underline{k}_e} \cdot \frac{\bar{\theta}_e - \theta}{\bar{\theta}_e - \underline{\theta}_e} +$$

$$c_{\text{node3}} \frac{k - \underline{k}_e}{\bar{k}_e - \underline{k}_e} \cdot \frac{\theta - \underline{\theta}_e}{\bar{\theta}_e - \underline{\theta}_e} + c_{\text{node4}} \frac{\bar{k}_e - k}{\bar{k}_e - \underline{k}_e} \cdot \frac{\theta - \underline{\theta}_e}{\bar{\theta}_e - \underline{\theta}_e}$$

calculate next period capital,  $K = \theta k^\alpha - c + (1 - \delta)k$

calculate next period's marginal product of capital  $mp_K = \alpha K^{\alpha-1}$

set  $s = 0$

do  $l = 1$  to  $m_e$

set  $\epsilon$  equal to the  $l$ th quadrature point (calculated in step 1(v)a)

calculate the next period shock,  $\Theta = \theta^\rho \exp(\epsilon)$

determine the element that includes point  $(K, \Theta)$  and call it  $E$

determine the 4 global nodes for element  $E$  (denote by NODEs 1-4)

calculate next period consumption  $C$ ,

e.g., if  $(K, \Theta)$  are the coordinates and  $E$  is the element, then

$$C = c_{\text{NODE1}} \frac{\bar{k}_E - K}{\bar{k}_E - \underline{k}_E} \cdot \frac{\bar{\theta}_E - \Theta}{\bar{\theta}_E - \underline{\theta}_E} + c_{\text{NODE2}} \frac{K - \underline{k}_E}{\bar{k}_E - \underline{k}_E} \cdot \frac{\bar{\theta}_E - \Theta}{\bar{\theta}_E - \underline{\theta}_E} +$$

$$c_{\text{NODE3}} \frac{K - \underline{k}_E}{\bar{k}_E - \underline{k}_E} \cdot \frac{\Theta - \underline{\theta}_E}{\bar{\theta}_E - \underline{\theta}_E} + c_{\text{NODE4}} \frac{\bar{k}_E - K}{\bar{k}_E - \underline{k}_E} \cdot \frac{\Theta - \underline{\theta}_E}{\bar{\theta}_E - \underline{\theta}_E}$$

calculate next period's marginal utility ( $mu = \beta C^{-\tau}$ )

add  $(mu \times \Theta mp_K + 1 - \delta \times f(\epsilon) \times l$ th quadrature weight) to  $s$

calculate derivatives of  $s$  with respect to  $c_a$  for all nodes  $a$

end loop over  $l$

compute residual:  $R = s - c^{-\tau}$

update elements of  $H$  associated with global nodes for element  $e$ ,

e.g., if  $(k, \theta)$  are the current coordinates, if element  $e$  is given by

$[\underline{k}_e, \bar{k}_e] \times [\underline{\theta}_e, \bar{\theta}_e]$ , and if  $\omega_{i,j}$  are the  $(i, j)$  quadrature weights, then

$$H(\text{node } 1) = H(\text{node } 1) + \omega_{i,j} \times R \times \frac{\bar{k}_e - k}{\bar{k}_e - \underline{k}_e} \cdot \frac{\bar{\theta}_e - \theta}{\bar{\theta}_e - \underline{\theta}_e}$$

$$H(\text{node } 2) = H(\text{node } 2) + \omega_{i,j} \times R \times \frac{k-k_e}{k_e-k_e} \cdot \frac{\bar{\theta}_e - \theta}{\theta_e - \underline{\theta}_e}$$

$$H(\text{node } 3) = H(\text{node } 3) + \omega_{i,j} \times R \times \frac{k-k_e}{k_e-k_e} \cdot \frac{\theta - \underline{\theta}_e}{\theta_e - \underline{\theta}_e}$$

$$H(\text{node } 4) = H(\text{node } 4) + \omega_{i,j} \times R \times \frac{\bar{k}_e - k}{k_e - k_e} \cdot \frac{\theta - \underline{\theta}_e}{\theta_e - \underline{\theta}_e}$$

calculate derivatives of  $H(\text{node } l)$ ,  $l = 1, 2, 3, 4$  with respect to ...

unknowns  $c_a$  for all nodes  $a$  and put the answer in the node  $l$ th ...

row of  $J$  (this calculation uses the derivatives of  $s$  and  $c^{-\tau}$ )

end loops over  $i, j$

end loop over  $e$

if  $k_1 = 0$ , enforce  $c(0, \theta) = 0$ , i.e., eliminate elements for  $k = 0$  nodes from  $H$  and  $J$

solve  $Jx = H$  for  $x$  and update the consumption vector:  $\vec{c} = \vec{c} - x$

if  $\|x\| < \text{tolerance}$ , go to step 4

end loop over  $t$

4. *Print results.*